

at a fixed frequency, is

$$i = I_0 \sin \omega t, \quad (15.2)$$

where i is the current at time t and I_0 is the peak current and is equal to V_0/R . For this example, the voltage and current are said to be in phase, meaning that their sinusoidal functional forms have peaks, troughs, and nodes in the same place. They oscillate in sync with each other, as shown in **Figure 15.2(b)**. In these equations, and throughout this chapter, we use lowercase letters (such as i) to indicate instantaneous values and capital letters (such as I) to indicate maximum, or peak, values.

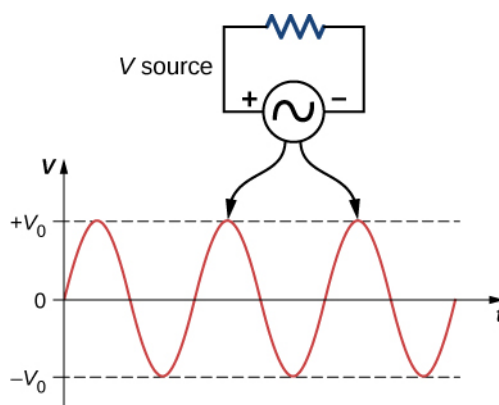


Figure 15.3 The potential difference V between the terminals of an ac voltage source fluctuates, so the source and the resistor have ac sine waves on top of each other. The mathematical expression for v is given by $v = V_0 \sin \omega t$.

Current in the resistor alternates back and forth just like the driving voltage, since $I = V/R$. If the resistor is a fluorescent light bulb, for example, it brightens and dims 120 times per second as the current repeatedly goes through zero. A 120-Hz flicker is too rapid for your eyes to detect, but if you wave your hand back and forth between your face and a fluorescent light, you will see the stroboscopic effect of ac.



15.1 Check Your Understanding If a European ac voltage source is considered, what is the time difference between the zero crossings on an ac voltage-versus-time graph?

15.2 | Simple AC Circuits

Learning Objectives

By the end of the section, you will be able to:

- Interpret phasor diagrams and apply them to ac circuits with resistors, capacitors, and inductors
- Define the reactance for a resistor, capacitor, and inductor to help understand how current in the circuit behaves compared to each of these devices

In this section, we study simple models of ac voltage sources connected to three circuit components: (1) a resistor, (2) a capacitor, and (3) an inductor. The power furnished by an ac voltage source has an emf given by

$$v(t) = V_0 \sin \omega t,$$

as shown in **Figure 15.4**. This sine function assumes we start recording the voltage when it is $v = 0 \text{ V}$ at a time of $t = 0 \text{ s}$. A phase constant may be involved that shifts the function when we start measuring voltages, similar to the phase

constant in the waves we studied in [Waves \(http://cnx.org/content/m58367/latest/\)](http://cnx.org/content/m58367/latest/). However, because we are free to choose when we start examining the voltage, we can ignore this phase constant for now. We can measure this voltage across the circuit components using one of two methods: (1) a quantitative approach based on our knowledge of circuits, or (2) a graphical approach that is explained in the coming sections.

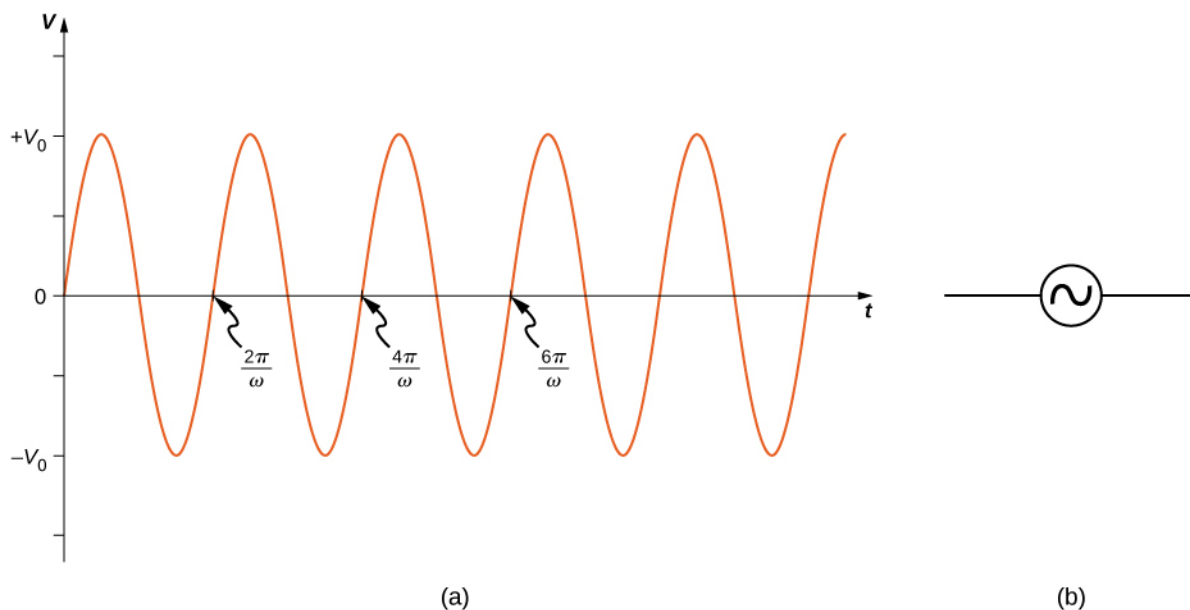


Figure 15.4 (a) The output $v(t) = V_0 \sin \omega t$ of an ac generator. (b) Symbol used to represent an ac voltage source in a circuit diagram.

Resistor

First, consider a resistor connected across an ac voltage source. From Kirchhoff's loop rule, the instantaneous voltage across the resistor of [Figure 15.5\(a\)](#) is

$$v_R(t) = V_0 \sin \omega t$$

and the instantaneous current through the resistor is

$$i_R(t) = \frac{v_R(t)}{R} = \frac{V_0}{R} \sin \omega t = I_0 \sin \omega t.$$

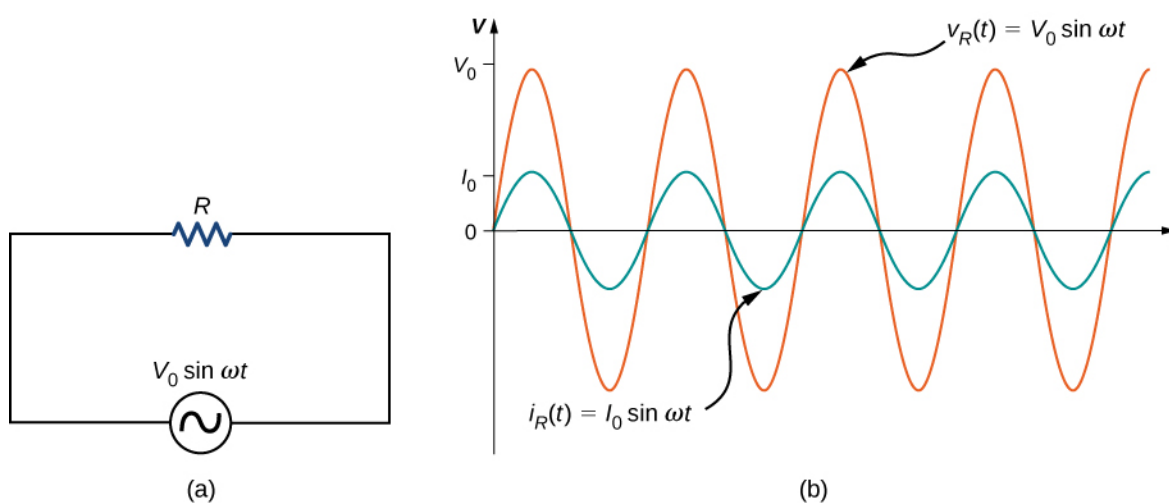


Figure 15.5 (a) A resistor connected across an ac voltage source. (b) The current $i_R(t)$ through the resistor and the voltage $v_R(t)$ across the resistor. The two quantities are in phase.

Here, $I_0 = V_0/R$ is the amplitude of the time-varying current. Plots of $i_R(t)$ and $v_R(t)$ are shown in **Figure 15.5(b)**. Both curves reach their maxima and minima at the same times, that is, the current through and the voltage across the resistor are in phase.

Graphical representations of the phase relationships between current and voltage are often useful in the analysis of ac circuits. Such representations are called *phasor diagrams*. The phasor diagram for $i_R(t)$ is shown in **Figure 15.6(a)**, with the current on the vertical axis. The arrow (or phasor) is rotating counterclockwise at a constant angular frequency ω , so we are viewing it at one instant in time. If the length of the arrow corresponds to the current amplitude I_0 , the projection of the rotating arrow onto the vertical axis is $i_R(t) = I_0 \sin \omega t$, which is the instantaneous current.

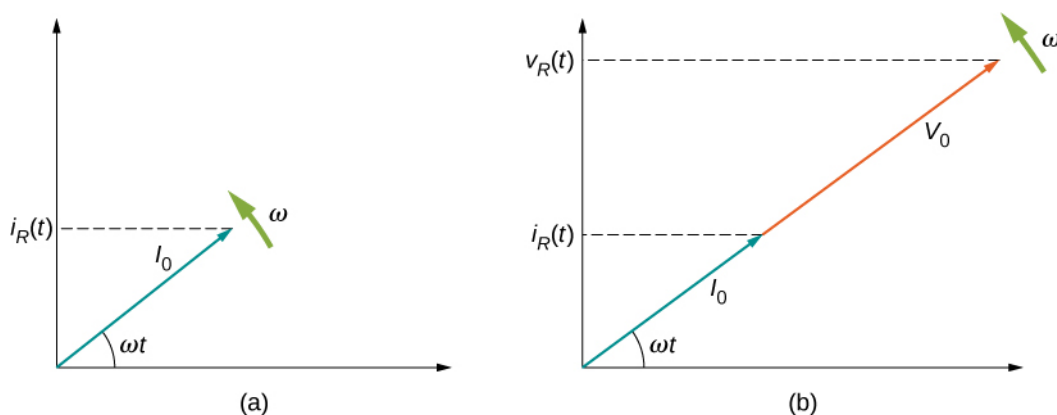


Figure 15.6 (a) The phasor diagram representing the current through the resistor of **Figure 15.5**. (b) The phasor diagram representing both $i_R(t)$ and $v_R(t)$.

The vertical axis on a phasor diagram could be either the voltage or the current, depending on the phasor that is being examined. In addition, several quantities can be depicted on the same phasor diagram. For example, both the current $i_R(t)$ and the voltage $v_R(t)$ are shown in the diagram of **Figure 15.6(b)**. Since they have the same frequency and are in phase, their phasors point in the same direction and rotate together. The relative lengths of the two phasors are arbitrary because they represent different quantities; however, the ratio of the lengths of the two phasors can be represented by the resistance, since one is a voltage phasor and the other is a current phasor.

Capacitor

Now let's consider a capacitor connected across an ac voltage source. From Kirchhoff's loop rule, the instantaneous voltage across the capacitor of **Figure 15.7(a)** is

$$v_C(t) = V_0 \sin \omega t.$$

Recall that the charge in a capacitor is given by $Q = CV$. This is true at any time measured in the ac cycle of voltage. Consequently, the instantaneous charge on the capacitor is

$$q(t) = Cv_C(t) = CV_0 \sin \omega t.$$

Since the current in the circuit is the rate at which charge enters (or leaves) the capacitor,

$$i_C(t) = \frac{dq(t)}{dt} = \omega CV_0 \cos \omega t = I_0 \cos \omega t,$$

where $I_0 = \omega CV_0$ is the current amplitude. Using the trigonometric relationship $\cos \omega t = \sin(\omega t + \pi/2)$, we may express the instantaneous current as

$$i_C(t) = I_0 \sin\left(\omega t + \frac{\pi}{2}\right).$$

Dividing V_0 by I_0 , we obtain an equation that looks similar to Ohm's law:

$$\frac{V_0}{I_0} = \frac{1}{\omega C} = X_C. \quad (15.3)$$

The quantity X_C is analogous to resistance in a dc circuit in the sense that both quantities are a ratio of a voltage to a current. As a result, they have the same unit, the ohm. Keep in mind, however, that a capacitor stores and discharges electric energy, whereas a resistor dissipates it. The quantity X_C is known as the **capacitive reactance** of the capacitor, or the opposition of a capacitor to a change in current. It depends inversely on the frequency of the ac source—high frequency leads to low capacitive reactance.

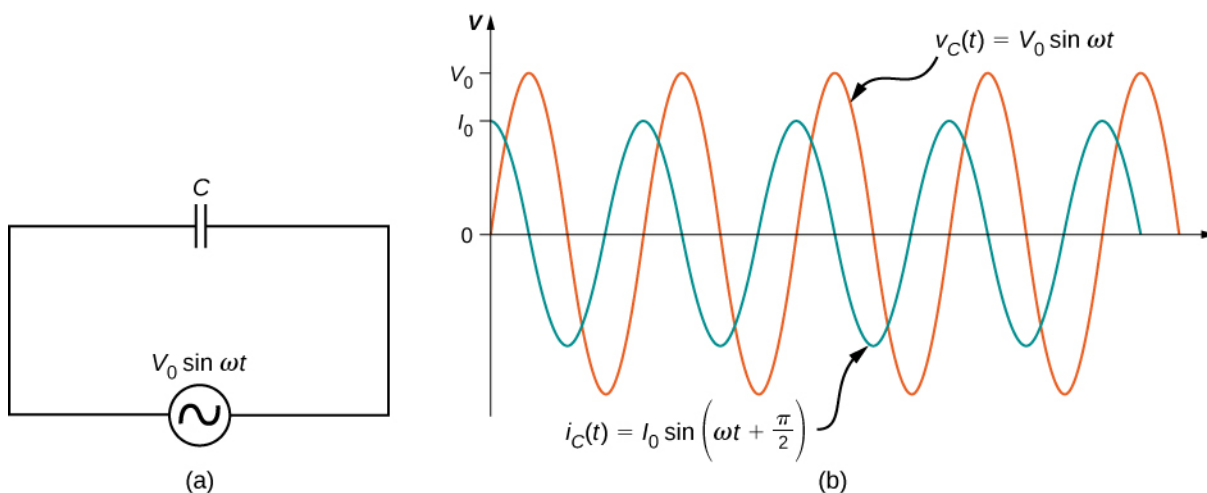


Figure 15.7 (a) A capacitor connected across an ac generator. (b) The current $i_C(t)$ through the capacitor and the voltage $v_C(t)$ across the capacitor. Notice that $i_C(t)$ leads $v_C(t)$ by $\pi/2$ rad.

A comparison of the expressions for $v_C(t)$ and $i_C(t)$ shows that there is a phase difference of $\pi/2$ rad between them. When these two quantities are plotted together, the current peaks a quarter cycle (or $\pi/2$ rad) ahead of the voltage, as illustrated in **Figure 15.7(b)**. The current through a capacitor leads the voltage across a capacitor by $\pi/2$ rad, or a quarter of a cycle.

The corresponding phasor diagram is shown in **Figure 15.8**. Here, the relationship between $i_C(t)$ and $v_C(t)$ is represented by having their phasors rotate at the same angular frequency, with the current phasor leading by $\pi/2$ rad.

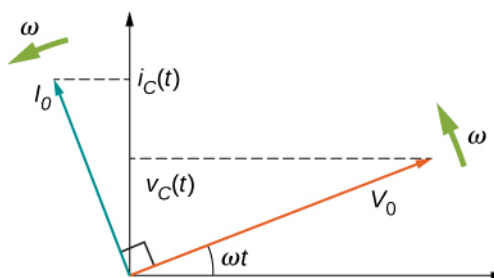


Figure 15.8 The phasor diagram for the capacitor of **Figure 15.7**. The current phasor leads the voltage phasor by $\pi/2$ rad as they both rotate with the same angular frequency.

To this point, we have exclusively been using peak values of the current or voltage in our discussion, namely, I_0 and V_0 . However, if we average out the values of current or voltage, these values are zero. Therefore, we often use a second convention called the root mean square value, or rms value, in discussions of current and voltage. The rms operates in

reverse of the terminology. First, you square the function, next, you take the mean, and then, you find the square root. As a result, the rms values of current and voltage are not zero. Appliances and devices are commonly quoted with rms values for their operations, rather than peak values. We indicate rms values with a subscript attached to a capital letter (such as I_{rms}).

Although a capacitor is basically an open circuit, an **rms current**, or the root mean square of the current, appears in a circuit with an ac voltage applied to a capacitor. Consider that

$$I_{\text{rms}} = \frac{I_0}{\sqrt{2}}, \quad (15.4)$$

where I_0 is the peak current in an ac system. The **rms voltage**, or the root mean square of the voltage, is

$$V_{\text{rms}} = \frac{V_0}{\sqrt{2}}, \quad (15.5)$$

where V_0 is the peak voltage in an ac system. The rms current appears because the voltage is continually reversing, charging, and discharging the capacitor. If the frequency goes to zero, which would be a dc voltage, X_C tends to infinity, and the current is zero once the capacitor is charged. At very high frequencies, the capacitor's reactance tends to zero—it has a negligible reactance and does not impede the current (it acts like a simple wire).

Inductor

Lastly, let's consider an inductor connected to an ac voltage source. From Kirchhoff's loop rule, the voltage across the inductor L of **Figure 15.9(a)** is

$$v_L(t) = V_0 \sin \omega t. \quad (15.6)$$

The emf across an inductor is equal to $\varepsilon = -L(di_L/dt)$; however, the potential difference across the inductor is $v_L(t) = L di_L(t)/dt$, because if we consider that the voltage around the loop must equal zero, the voltage gained from the ac source must dissipate through the inductor. Therefore, connecting this with the ac voltage source, we have

$$\frac{di_L(t)}{dt} = \frac{V_0}{L} \sin \omega t.$$

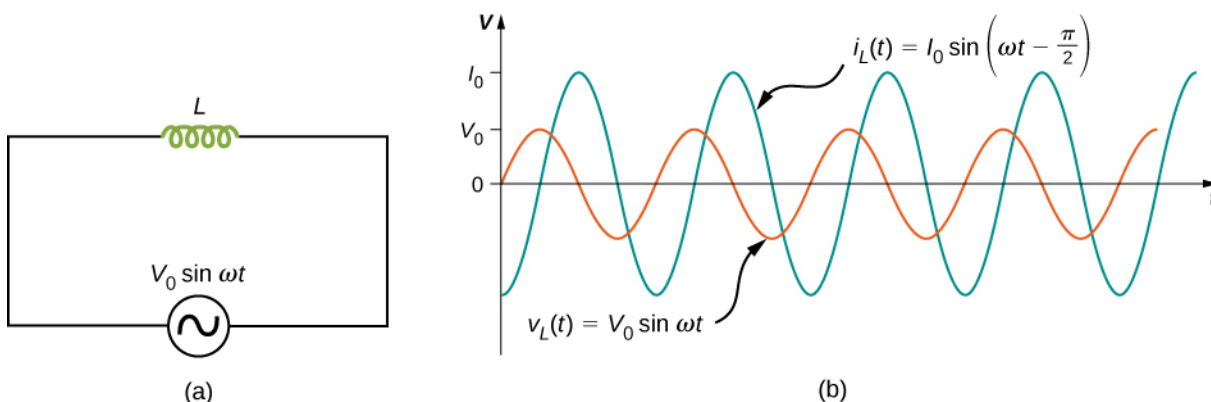


Figure 15.9 (a) An inductor connected across an ac generator. (b) The current $i_L(t)$ through the inductor and the voltage $v_L(t)$ across the inductor. Here $i_L(t)$ lags $v_L(t)$ by $\pi/2$ rad.

The current $i_L(t)$ is found by integrating this equation. Since the circuit does not contain a source of constant emf, there

is no steady current in the circuit. Hence, we can set the constant of integration, which represents the steady current in the circuit, equal to zero, and we have

$$i_L(t) = -\frac{V_0}{\omega L} \cos \omega t = \frac{V_0}{\omega L} \sin\left(\omega t - \frac{\pi}{2}\right) = I_0 \sin\left(\omega t - \frac{\pi}{2}\right), \quad (15.7)$$

where $I_0 = V_0/\omega L$. The relationship between V_0 and I_0 may also be written in a form analogous to Ohm's law:

$$\frac{V_0}{I_0} = \omega L = X_L. \quad (15.8)$$

The quantity X_L is known as the **inductive reactance** of the inductor, or the opposition of an inductor to a change in current; its unit is also the ohm. Note that X_L varies directly as the frequency of the ac source—high frequency causes high inductive reactance.

A phase difference of $\pi/2$ rad occurs between the current through and the voltage across the inductor. From **Equation 15.6** and **Equation 15.7**, the current through an inductor lags the potential difference across an inductor by $\pi/2$ rad, or a quarter of a cycle. The phasor diagram for this case is shown in **Figure 15.10**.

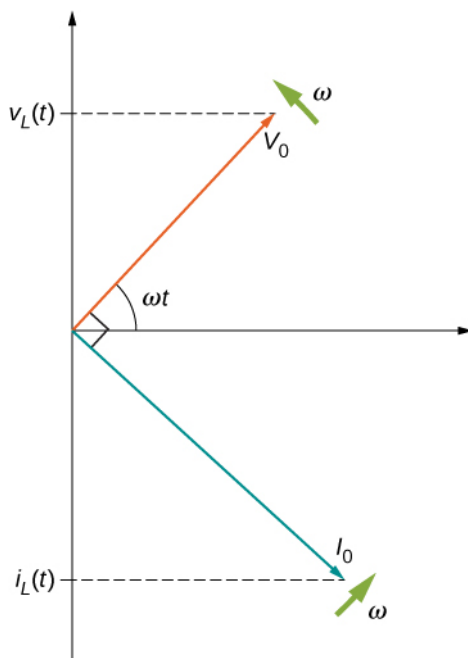


Figure 15.10 The phasor diagram for the inductor of **Figure 15.9**. The current phasor lags the voltage phasor by $\pi/2$ rad as they both rotate with the same angular frequency.



An animation from the University of New South Wales **AC Circuits** (<https://openstaxcollege.org//21accircuits>) illustrates some of the concepts we discuss in this chapter. They also include wave and phasor diagrams that evolve over time so that you can get a better picture of how each changes over time.

Example 15.1

Simple AC Circuits

An ac generator produces an emf of amplitude 10 V at a frequency $f = 60$ Hz. Determine the voltages across and the currents through the circuit elements when the generator is connected to (a) a $100\text{-}\Omega$ resistor, (b) a $10\text{-}\mu\text{F}$ capacitor, and (c) a 15-mH inductor.

Strategy

The entire AC voltage across each device is the same as the source voltage. We can find the currents by finding the reactance X of each device and solving for the peak current using $I_0 = V_0/X$.

Solution

The voltage across the terminals of the source is

$$v(t) = V_0 \sin \omega t = (10\text{ V}) \sin 120\pi t,$$

where $\omega = 2\pi f = 120\pi$ rad/s is the angular frequency. Since $v(t)$ is also the voltage across each of the elements, we have

$$v(t) = v_R(t) = v_C(t) = v_L(t) = (10\text{ V}) \sin 120\pi t.$$

a. When $R = 100\text{ }\Omega$, the amplitude of the current through the resistor is

$$I_0 = V_0/R = 10\text{ V}/100\text{ }\Omega = 0.10\text{ A},$$

so

$$i_R(t) = (0.10\text{ A}) \sin 120\pi t.$$

b. From **Equation 15.3**, the capacitive reactance is

$$X_C = \frac{1}{\omega C} = \frac{1}{(120\pi\text{ rad/s})(10 \times 10^{-6}\text{ F})} = 265\text{ }\Omega,$$

so the maximum value of the current is

$$I_0 = \frac{V_0}{X_C} = \frac{10\text{ V}}{265\text{ }\Omega} = 3.8 \times 10^{-2}\text{ A}$$

and the instantaneous current is given by

$$i_C(t) = (3.8 \times 10^{-2}\text{ A}) \sin\left(120\pi t + \frac{\pi}{2}\right).$$

c. From **Equation 15.8**, the inductive reactance is

$$X_L = \omega L = (120\pi\text{ rad/s})(15 \times 10^{-3}\text{ H}) = 5.7\text{ }\Omega.$$

The maximum current is therefore

$$I_0 = \frac{10\text{ V}}{5.7\text{ }\Omega} = 1.8\text{ A}$$

and the instantaneous current is

$$i_L(t) = (1.8\text{ A}) \sin\left(120\pi t - \frac{\pi}{2}\right).$$

Significance

Although the voltage across each device is the same, the peak current has different values, depending on the reactance. The reactance for each device depends on the values of resistance, capacitance, or inductance.



15.2 Check Your Understanding Repeat **Example 15.1** for an ac source of amplitude 20 V and frequency 100 Hz.

15.3 | RLC Series Circuits with AC

Learning Objectives

By the end of the section, you will be able to:

- Describe how the current varies in a resistor, a capacitor, and an inductor while in series with an ac power source
- Use phasors to understand the phase angle of a resistor, capacitor, and inductor ac circuit and to understand what that phase angle means
- Calculate the impedance of a circuit

The ac circuit shown in **Figure 15.11**, called an *RLC* series circuit, is a series combination of a resistor, capacitor, and inductor connected across an ac source. It produces an emf of

$$v(t) = V_0 \sin \omega t.$$

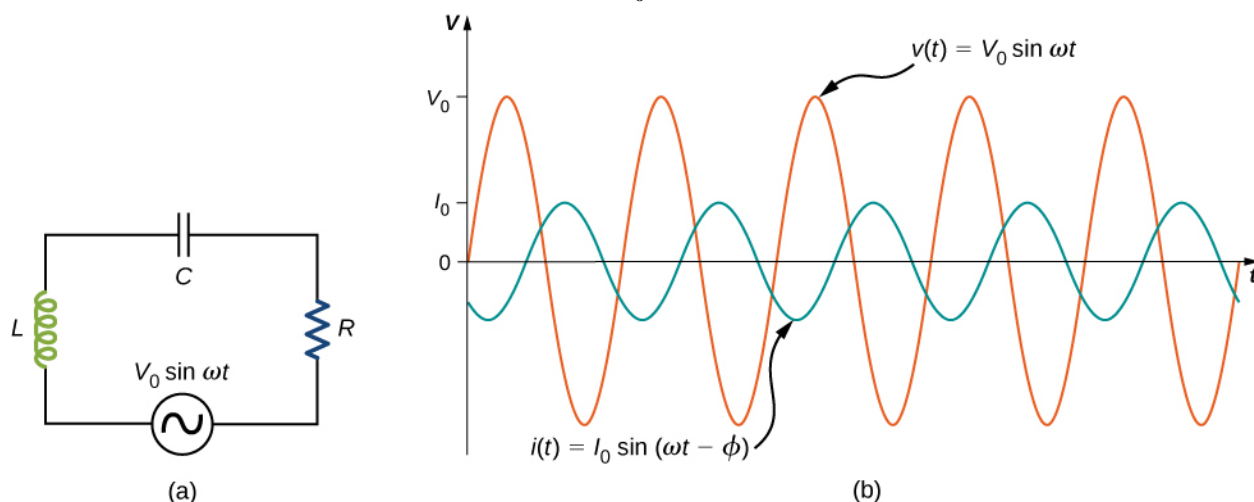


Figure 15.11 (a) An *RLC* series circuit. (b) A comparison of the generator output voltage and the current. The value of the phase difference ϕ depends on the values of R , C , and L .

Since the elements are in series, the same current flows through each element at all points in time. The relative phase between the current and the emf is not obvious when all three elements are present. Consequently, we represent the current by the general expression

$$i(t) = I_0 \sin(\omega t - \phi),$$

where I_0 is the current amplitude and ϕ is the **phase angle** between the current and the applied voltage. The phase angle is thus the amount by which the voltage and current are out of phase with each other in a circuit. Our task is to find I_0 and ϕ .

A phasor diagram involving $i(t)$, $v_R(t)$, $v_C(t)$, and $v_L(t)$ is helpful for analyzing the circuit. As shown in **Figure 15.12**, the phasor representing $v_R(t)$ points in the same direction as the phasor for $i(t)$; its amplitude is $V_R = I_0 R$. The $v_C(t)$ phasor lags the $i(t)$ phasor by $\pi/2$ rad and has the amplitude $V_C = I_0 X_C$. The phasor for $v_L(t)$ leads the $i(t)$ phasor by $\pi/2$ rad and has the amplitude $V_L = I_0 X_L$.